Expectation and Moments

Yuki Shiraito

POLSCI 599 Statistical Methods in Political Research I University of Michigan Conditional Expectation

Expectation

- Summary of r.v. X:
 - What is the gain you expect from a lottery?
 - What is the number of Dems you expect in a sample?
 - What is the lifetime income you expect from an academic job?
- Expectation or expected value of X: Weighted average of X where the weights are the probability measure of events X = x
- For a discrete r.v. X,

$$\mathbb{E}[X] = \sum_{x} x f_X(x)$$

• For a continuous r.v. X,

$$\mathbb{E}[X] = \int_X x f_X(x) dx$$

• $X \sim \text{Bern}(p) \Rightarrow \mathbb{E}[X] = p$ • $X \sim \text{Unif}(0, 1) \Rightarrow \mathbb{E}[X] = 1/2$

Existence of Expectation

- Expectation does not always exist
- Existence of expectation: $\mathbb{E}[X]$ exists if and only if $\mathbb{E}[X_{-}] < \infty$ or
 - $\mathbb{E}[X_+] < \infty, \text{ where } X_- \equiv -\min\{X, 0\} \text{ and } X_+ \equiv \max\{X, 0\}.$
 - $\mathbb{E}[X_{-}] < \infty$ and $\mathbb{E}[X_{+}] < \infty$: $-\infty < \mathbb{E}[X] < \infty$ • $\mathbb{E}[X_{-}] < \infty$ and $\mathbb{E}[X_{-}] = \infty$: $\mathbb{E}[X] = -\infty$ • $\mathbb{E}[X_{+}] = \infty$ and $\mathbb{E}[X_{-}] < \infty$: $\mathbb{E}[X] = \infty$ • $\mathbb{E}[X_{+}] = \infty$ and $\mathbb{E}[X_{-}] = \infty$: $\mathbb{E}[X]$ does not exist
- Expectation can be infinity, but its sign should be well defined
- X follows the standard Cauchy distribution:

$$f_X(x) = \frac{1}{n(1+x^2)}$$
 for $-\infty < x < \infty$

- Valid p.d.f: $\int_{-\infty}^{\infty} f(x) dx = [\tan^{-1}(x)/n]_{-\infty}^{\infty} = \{n/2 (-n/2)\}/n = 1$
- $\int_0^\infty x f(x) dx = [\log(1+x^2)/2]_0^\infty = \infty$
- Similarly, $\int_{-\infty}^{0} -xf(x)dx = [\log(1+x^2)/2]_{-\infty}^{0} = \infty$
- Expectation does not exist for the Cauchy distribution

Indicator and Linearity

- Expectation of Indicator: For a probability space $(\Omega, \mathcal{F}, \mathbb{P})$, let A be an event and define r.v. $1_A \equiv 1\{\omega \in A\}$. Then, $\mathbb{E}[1_A] = \mathbb{P}(A)$
- Corollary: Let $C \subset \mathbb{R}$. For r.v. X, define $1_C(X) \equiv 1\{X \in C\}$. Then, $\mathbb{E}[1_C(X)] = \mathbb{P}(X \in C)$
- Dice roll: X is the number on the face
 - Let $C \equiv \{2, 3, 4, 5\}$

•
$$\mathbb{P}(X \in C) = 2/3$$

- $\mathbb{E}[1_C(X)] = 1 \times (4 \times 1/6) + 0 \times (2 \times 1/6) = 2/3$
- Linearity: Let X_1, X_2 be r.v.s. Then, $\mathbb{E}[aX_1 + bX_2 + c] = a\mathbb{E}[X_1] + b\mathbb{E}[X_2] + c$
- Binomial expectation:
 - By definition of expactation,

$$\mathbb{E}[X] = \sum_{x=0}^{n} x \binom{n}{x} p^{x} (1-p)^{n-x} = np \sum_{x=1}^{n} \binom{n-1}{x-1} p^{x-1} (1-p)^{n-x} = np$$

• Binom(n,p) is the distribution of $\sum_{i=1}^{n} X_i$ where $X_i \stackrel{\text{i.i.d.}}{\sim} \text{Bern}(p)$

$$\mathbb{E}[X] = \mathbb{E}[X_1] + \dots + \mathbb{E}[X_n] = np$$

Random Vectors

• Expectation of random vector: For a random vector X, its expectation is defined as

 $\mathbb{E}[\mathsf{X}] \equiv (\mathbb{E}[X_1], \dots, \mathbb{E}[X_n])$

where the expectation of X_i is over its marginal distribution

Multinomial distribution X ~ Multi(n, p):
 Marginal distribution of X₁ is Binomial:

$$\mathbb{P}(X_1 = x_1) = \sum_{x_2...x_K} \frac{n!}{x_1! \dots x_K!} p_1^{x_1} \dots p_K^{x_K}$$

= $\frac{n!}{x_1!(n-x_1)!} p_1^{x_1} \sum_{x_2...x_K} \frac{(n-x_1)!}{x_2! \dots x_K!} p_2^{x_2} \dots p_K^{x_K}$
= $\frac{n!}{x_1!(n-x_1)!} p_1^{x_1} (1-p_1)^{n-x_1}$

2 $\mathbb{E}[X] = (np_1, \ldots, np_K)$

Functions and Product

• Expectation of functions of r.v.: Let X be a r.v. and $g : \mathbb{R} \to \mathbb{R}$. Then,

$$\mathbb{E}[g(X)] = \begin{cases} \sum_{x} g(x) f_X(x) & (X \text{ discrete}) \\ \int_{X} g(x) f_X(x) dx & (X \text{ continuous}) \end{cases}$$

Proof. Directly follows from the fact that for any $C \subset \mathbb{R}$, $\mathbb{P}(g(X) \in C) = \mathbb{P}(X \in \{x \in \mathbb{R} \mid g(x) \in C\})$

• *X* follows a Geometric distribution, *X* ~ Geom(*p*):

$$f_X(x) = (1-p)^{x-1}p$$
, for $x = 1, 2, ...$

St. Petersburg paradox: g(x) ≡ 2^x ⇒ E[g(X)] = ∞ if p = 1/2
 E[g(X)] ≠ g(E[X]) in general: E[X] = 2

- Lemma: Let X be a discrete r.v. whose support is the non-negative integers. Then, $\mathbb{E}[X] = \sum_{x=1}^{\infty} \mathbb{P}(X \ge x)$
- Product of independent r.v.s: Let X_i , i = 1, ..., n are independent. Then, $\mathbb{E}[\prod_{i=1}^{n} X_n] = \prod_{i=1}^{n} \mathbb{E}[X_i]$

•
$$X_i \stackrel{\text{i.i.d.}}{\sim} \text{Bern}(p) \Rightarrow \mathbb{P}(X_1 = 1, \dots, X_n = 1) = p^n$$

Inequalities of Expectation

- If $X_1 \leq X_2$ with probability 1, i.e., $X_1(\omega) \leq X_2(\omega)$ for all $\omega \in \Omega$, then $\mathbb{E}[X_1] \leq \mathbb{E}[X_2]$
- If $a \leq X \leq b$ with probability 1, i.e., $a \leq X(\omega) \leq b$ for all $\omega \in \Omega$, then $a \leq \mathbb{E}[X] \leq b$
- Jensen's inequality: Let $g : \mathbb{R} \to \mathbb{R}$ be a concave (convex) function. Then, for a random vector X, $\mathbb{E}[g(X)] \le (\ge)g(\mathbb{E}[X])$
- Concave function: A function g : ℝⁿ → ℝ is concave if and only if for every a ∈ (0, 1), g(ax + (1 - a)y) ≥ ag(x) + (1 - a)g(y) for any x, y ∈ ℝⁿ
- Logarithm is common in statistics: $\mathbb{E}[\log(X)] < \log(\mathbb{E}[X])$

onditional Expectation

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Moments and Variance

- Moments of an r.v.: For an r.v. X and a positive integer k, $\mathbb{E}[X^k]$ is called the *k*th *moment* of X
- Existence of moments: If $\mathbb{E}[X^k]$ exists, $\mathbb{E}[X^l]$ exists for any l < k
- Central moments: $\mathbb{E}[(X \mathbb{E}[X])^k]$ is called the *k*th central moment or the *k*th moment of *X* about the mean
- If the *k*th moment exists, the *l*th central moment exists for $l \le k$
- Variance: The second centeral moment of X is called the variance of X, denoted by $\mathbb{V}(X) \equiv \mathbb{E}[(X \mathbb{E}[X])^2]$
- Variance and moments: $\mathbb{V}(X) = \mathbb{E}[X^2] (\mathbb{E}[X])^2$
- $\mathbb{V}(X) \ge 0$, with equality if and only if $\mathbb{P}(X = c) = 1$ for some c
- $Y = aX + b \Rightarrow \mathbb{V}(Y) = a^2 \mathbb{V}(X)$
- Variance of $\operatorname{Bern}(p)$: $\mathbb{E}[X^2] (\mathbb{E}[X])^2 = p p^2 = p(1-p)$

Conditional Expectation

Covariance

- Covariance: For r.v.s X_1 and X_2 , the covariance of X_1 and X_2 , denoted by $Cov(X_1, X_2)$, is defined as: $Cov(X_1, X_2) \equiv \mathbb{E}[(X_1 - \mathbb{E}[X_1])(X_2 - \mathbb{E}[X_2])]$
- Analogously to the variance, $Cov(X_1, X_2) = \mathbb{E}[X_1X_2] \mathbb{E}[X_1]\mathbb{E}[X_2]$
- Correlation: The correlation of X_1 and X_2 , denoted by $\rho(X_1, X_2)$, is defined as:

$$\rho(X_1, X_2) \equiv \frac{\operatorname{Cov}(X_1, X_2)}{\sqrt{\mathbb{V}(X_1)\mathbb{V}(X_2)}}$$

•
$$\rho(X_1, X_2) = \operatorname{Cov}\left((X_1 - \mathbb{E}[X_1])/\sqrt{\mathbb{V}(X_1)}, (X_2 - \mathbb{E}[X_2])/\sqrt{\mathbb{V}(X_2)}\right)$$

- Covariance depends on the scale of r.v.s, but $|\rho(X_1, X_2)| \le 1$
- X_1 and X_2 are *uncorrelated* if and only if $Cov(X_1, X_2) = 0$
- X_1 and X_2 are independent $\Rightarrow X_1$ and X_2 are uncorrelated
- The converse does not necessarily hold:
 - $U \sim \text{Unif}(0, 1), X_1 = \cos 2\pi U \text{ and } X_2 = \sin 2\pi U$
 - Clearly, X_1 and X_2 are not independent, but $Cov(X_1, X_2) = 0$
- Covariance and correlation indicate *linear* relationship b/w r.v.s

Variance-Covariance Matrix

- Trivially, $\mathbb{V}(X) = \mathbb{E}[(X \mathbb{E}[X])(X \mathbb{E}[X])] = Cov(X, X)$
- Variance-covariance Matrix: For r.v.s X_1, \ldots, X_n , we define the *(variance-)covariance matrix,* denoted by $\mathbb{V}(X)$ or Σ_X , as

$$\Sigma_{\mathbf{X}} \equiv \begin{pmatrix} \mathbb{V}(X_1) & \mathsf{Cov}(X_1, X_2) & \cdots & \mathsf{Cov}(X_1, X_n) \\ \mathsf{Cov}(X_2, X_1) & \mathbb{V}(X_2) & \cdots & \mathsf{Cov}(X_2, X_n) \\ \vdots & \vdots & \ddots & \vdots \\ \mathsf{Cov}(X_n, X_1) & \mathsf{Cov}(X_n, X_2) & \cdots & \mathbb{V}(X_n) \end{pmatrix}$$

- In vector notation, $\boldsymbol{\Sigma}_X = \mathbb{E}[(X \mathbb{E}[X])(X \mathbb{E}[X])^\top]$
- $\bullet~\Sigma_X$ is positive semi-definite
- Σ_X is positive definite unless some r.v.s are constant \Rightarrow invertible
- If X_1, \ldots, X_n are i.i.d., Σ_X is diagonal
- $\mathbb{V}\left(\sum_{i=1}^{n} a_i X_i\right) = \sum_{i=1}^{n} a_i^2 \mathbb{V}(X_i) + 2 \sum_{i < j} a_i a_j \operatorname{Cov}(X_i, X_j)$
- X_i s are uncorrelated, $\mathbb{V}\left(\sum_{i=1}^n X_i\right) = \sum_{i=1}^n \mathbb{V}(X_i)$

• If
$$X_1, \ldots, X_n$$
 are i.i.d., $\mathbb{V}\left(\sum_{i=1}^n X_i\right) = \operatorname{tr}(\Sigma_X)$

Conditional Expectation

- Summarizing prediction of *Y* using *X*:
 - Given X = x, Y is predicted by its conditional *distribution*
 - Conditional *expectation* is used to summarize the prediction
- Conditional expectation: The conditional expectation of Y given X, denoted by $\mathbb{E}[Y \mid X]$, is the expectation of the conditional distribution of Y given X
- Conditional moments are defined with expectation replaced by conditional expectation, e.g. $\mathbb{V}(Y \mid X) \equiv \mathbb{E}[(Y \mathbb{E}[Y \mid X])^2 \mid X]$
- Conditional expectation is an r.v.:
 - $\mathbb{E}[Y \mid X]$ is a function of X
 - $\mathbb{E}[Y \mid X]$ has a distribution defined by F_X
- Conditional expectation is expectation:
 - For any fixed x_1 , $\mathbb{E}[Y | X = x_1]$ is expectation
 - All the properties of expectation hold for $\mathbb{E}[Y | X = x_1]$
- Uniform-Binomial example:

$$\mathbb{E}[X_1 \mid X_2] = \int_0^1 x_1 \frac{x_1^{X_2} (1 - x_1)^{n - X_2}}{B(X_2 + 1, n - X_2 + 1)} dx_1 = \frac{X_2 + 1}{n + 2}$$

Properties of Conditional Expectation

• Law of iterated expectations: Let X and Y be r.v.s. Then, $\mathbb{E}\left[\mathbb{E}[g(X,Y) \mid X]\right] = \mathbb{E}[g(X,Y)]$

for any function g.

• Law of total variance: Let X and Y be r.v.s. Then, $\mathbb{E}\left[\mathbb{V}(Y \mid X)\right] + \mathbb{V}\left(\mathbb{E}[Y \mid X]\right) = \mathbb{V}(Y)$

• Uniform-Binomial example:

$$\mathbb{E}[X_2] = \mathbb{E}[nX_1] = \frac{n}{2}$$

$$\mathbb{V}[X_2] = \mathbb{E}[nX_1(1 - X_1)] + \mathbb{V}(nX_1) = \frac{n}{6} + \frac{n^2}{12}$$

• Minimization of expected squared distance (regression): Conditional expectation is the "best" predictor in the sense that $\underset{c}{\operatorname{argmin}} \mathbb{E}\left[(Y-c)^2 \mid X\right] = \mathbb{E}[Y \mid X]$ Proof.

$$\mathbb{E}\left[(Y-c)^2 \mid X\right] = \mathbb{E}\left[(Y-\mathbb{E}[Y \mid X])^2 \mid X\right] + \underbrace{(\mathbb{E}[Y \mid X] - c)^2}_{=0 \text{ iff } c = \mathbb{E}[Y \mid X]}$$

Standard Gaussian Distribution

- X follows the standard multivariate Gaussian distribution:
 - Joint p.d.f.: For a vector of real numbers $x \equiv x_1 \dots, x_K$,

$$f_{\mathbf{X}}(\mathbf{x}) = \frac{1}{(2\pi)^{K/2}} e^{-\frac{1}{2}\mathbf{x}^{\top}\mathbf{x}} = \prod_{k=1}^{K} \frac{1}{\sqrt{2\pi}} e^{-\frac{x_{k}^{2}}{2}}$$

- Denoted by: $X \sim \mathcal{N}(\mathbf{0}, \mathbf{I}_{\!\mathcal{K}})$
- X_1, \ldots, X_K are independent
- K = 1: The standard Gaussian (Normal) distribution $\mathcal{N}(0, 1)$
- Box-Muller Transfromation: Let U_1 and U_2 be independent uniform r.v.s. Define

$$\begin{split} X_1 &= \sqrt{-2\log U_1}\cos(2\pi U_2), \\ X_2 &= \sqrt{-2\log U_1}\sin(2\pi U_2). \end{split}$$

Then,

$$X \sim \mathcal{N}(0, \mathbf{I}_2)$$

• Random number generator for the Gaussian distributions

Yuki Shiraito

Change of Variables

• BH, 8.1; DS, p. 172-3, 182-6

• Change of variables: Let X be a continuous random vector of length K and $Y \equiv g(X)$ where $g : \mathbb{R}^K \to \mathbb{R}^K$ is one-to-one and differentiable. Then, the p.d.f. of Y is

$$f_{Y}(y)=f_{X}\left(g^{-1}(y)\right)\left|\det\left(\mathbf{J}(y)\right)\right|$$

where $g^{-1} : \mathbb{R}^K \to \mathbb{R}^K$ is the inverse function of g.

 $\mathbf{J}(\cdot)$ is the Jacobian (matrix) of g^{-1} defined as:

$$\mathbf{J}(\mathbf{y}) = \begin{pmatrix} \frac{\partial g_1^{-1}}{\partial y_1}(\mathbf{y}) & \cdots & \frac{\partial g_1^{-1}}{\partial y_K}(\mathbf{y}) \\ \vdots & \ddots & \vdots \\ \frac{\partial g_K^{-1}}{\partial y_1}(\mathbf{y}) & \cdots & \frac{\partial g_K^{-1}}{\partial y_K}(\mathbf{y}) \end{pmatrix}$$

where $g_i^{-1}(\mathbf{y})$ is the *i*th element of $g^{-1}(\mathbf{y})$.

Univariate Change of Variables

• Univariate change of variables: Let X be a continuous r.v. and $Y \equiv g(X)$ where $g : \mathbb{R} \to \mathbb{R}$ is one-to-one and differentiable. Then, the p.d.f. of Y is

$$f_Y(y) = f_X\left(g^{-1}(y)\right) \left|\frac{dg^{-1}}{dy}(y)\right|$$

Proof.

- If g(x) is one-to-one and differentiable, it is either strictly increasing or decreasing.
- Pirst, we assume that it is strictly increasing. Then, the c.d.f. of Y is

$$F_{Y}(y) = \mathbb{P}(Y \le y) = \mathbb{P}(g(X) \le y) = \mathbb{P}\left(X \le g^{-1}(y)\right) = F_{X}\left(g^{-1}(y)\right)$$

So the p.d.f. of Y is

$$\begin{aligned} F_Y(y) &= \frac{d}{dy} F_Y(y) = \frac{d}{dy} F_X\left(g^{-1}(y)\right) \\ &= f_X\left(g^{-1}(y)\right) \frac{dg^{-1}}{dy}(y) \quad (\because \text{ chain rule}) \end{aligned}$$

Proof, cont.

- **3** Because g is strictly increasing, we have $\frac{dg^{-1}}{dy}(y) > 0$ so that $\frac{dg^{-1}}{dy}(y) = \left|\frac{dg^{-1}}{dy}(y)\right|.$
- Second, we consider the case in which *g* is strictly decreasing. Then, the c.d.f. of *Y* is

$$F_Y(y) = \mathbb{P}(Y \le y) = \mathbb{P}(g(X) \le y) = \mathbb{P}\left(X \ge g^{-1}(y)\right)$$
$$= 1 - \mathbb{P}\left(X \le g^{-1}(y)\right) = 1 - F_X\left(g^{-1}(y)\right)$$

Note that the inequality is flipped because g is strictly decreasing.So the p.d.f. of Y is

$$f_{Y}(y) = \frac{d}{dy}F_{Y}(y) = \frac{d}{dy}\left(1 - F_{X}\left(g^{-1}(y)\right)\right)$$
$$= -f_{X}\left(g^{-1}(y)\right)\frac{dg^{-1}}{dy}(y) = f_{X}\left(g^{-1}(y)\right)\left(-\frac{dg^{-1}}{dy}(y)\right)$$

Because g is strictly decreasing, we have $\frac{dg^{-1}}{dy}(y) < 0$ so that $-\frac{dg^{-1}}{dy}(y) = \left|\frac{dg^{-1}}{dy}(y)\right|.$

Yuki Shiraito

Expectation

Conditional Expectation

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Box-Muller Transformation

• Inverse of the Box-Muller transformation:

$$\begin{array}{rcl} X_1 &=& \sqrt{-2\log U_1}\cos(2\pi U_2) & U_1 &=& e^{-(X_1^2 + X_2^2)/2} \\ X_2 &=& \sqrt{-2\log U_1}\sin(2\pi U_2) & \Leftrightarrow & U_2 &=& \frac{1}{2\pi}\arctan\left(\frac{X_2}{X_1}\right) \end{array}$$

• The determinant of the Jacobian is:

$$\begin{aligned} \det \left(\mathbf{J}(\mathbf{X}) \right) &= \det \left(\begin{array}{cc} \frac{\partial U_1}{\partial X_1} & \frac{\partial U_1}{\partial X_2} \\ \frac{\partial U_2}{\partial X_1} & \frac{\partial U_2}{\partial X_2} \end{array} \right) \\ &= \det \left(\begin{array}{cc} -X_1 e^{-(X_1^2 + X_2^2)/2} & -X_2 e^{-(X_1^2 + X_2^2)/2} \\ \frac{-X_2/X_1^2}{2\pi(1 + (X_2/X_1)^2)} & \frac{1/X_1}{2\pi(1 + (X_2/X_1)^2)} \end{array} \right) \\ &= \frac{-1 - X_2^2/X_1^2}{2\pi \left(1 + (X_2/X_1)^2\right)} e^{-(X_1^2 + X_2^2)/2} \\ &= -\frac{1}{\sqrt{2\pi}} e^{-X_1^2/2} \times \frac{1}{\sqrt{2\pi}} e^{-X_2^2/2} \end{aligned}$$

Linear Transformation of Gaussian

• *Linear transformation*: Let X be a *K*-dimensional random vector. A linear transformation of X is

$$\mathsf{Y} = \mathsf{a} + \mathbf{A}\mathsf{X}$$

where \mathbf{A} is a matrix with K columns

• Multivariate Gaussian: Let X follow the standard multivariate Gaussian distribution. Then, for a full rank $K \times K$ matrix **A** and an *K* dimensional vector μ , $\mathbf{Y} = \mu + \mathbf{A}\mathbf{X}$ has a p.d.f.:

$$f_{\mathbf{Y}}(\mathbf{y}) = \frac{1}{(2\pi)^{K/2} \det(\Sigma)^{1/2}} e^{-\frac{1}{2}(\mathbf{y}-\mu)^{\top} \Sigma^{-1}(\mathbf{y}-\mu)}$$

where $\Sigma = AA$ **Proof.**

$$X = \mathbf{A}^{-1}(Y - \mu)$$
$$J = \mathbf{A}^{-1}$$

- $\mathbb{E}[Y] = \mu$ and $\mathbb{V}(Y) = \Sigma$
- Uncorrelated ⇔ (pairwise) independent

Conditional and Marginal of Gaussian

• Let
$$(X_1, X_2)^{\top} \sim \mathcal{N}(\mu, \Sigma)$$
. The joint p.d.f. is:

$$f_{(X_1, X_2)}(x_1, x_2) = \frac{e^{-\frac{1}{2(1-\rho^2)} \left\{ \left(\frac{x_1 - \mu_1}{\sigma_1}\right)^2 - 2\rho \left(\frac{x_1 - \mu_1}{\sigma_1}\right) \left(\frac{x_2 - \mu_2}{\sigma_2}\right) + \left(\frac{x_2 - \mu_2}{\sigma_2}\right)^2 \right\}}{2\pi\sigma_1\sigma_2\sqrt{1-\rho^2}}$$

$$= \frac{e^{-\frac{1}{2(1-\rho^2)\sigma_2^2} \left(x_2 - \mu_2 - \rho\sigma_2 \frac{x_1 - \mu_1}{\sigma_1}\right)^2}}{\sqrt{2\pi\sigma_2}\sqrt{1-\rho^2}} \underbrace{\frac{e^{-\frac{1}{2} \left(\frac{x_1 - \mu_1}{\sigma_1}\right)^2}}{\sqrt{2\pi\sigma_1}}}_{f_{X_1}(x_1)}$$
• $X_1 \in \mathcal{N}(\mu, \sigma^2), X_2 \mid X_1 \in \mathcal{N}(\mu, \pm \frac{\rho\sigma_2}{\sigma_2}(X_1 - \mu_1)) \left(1 - \rho^2\right)\sigma^2$

- $X_1 \sim \mathcal{N}(\mu_1, \sigma_1^2), X_2 \mid X_1 \sim \mathcal{N}(\mu_2 + \frac{\rho \sigma_2}{\sigma_1}(X_1 \mu_1), (1 \rho^2)\sigma_2^2)$
- Both marginal and conditional distributions are Gaussian
- Regression $\mathbb{E}[X_2 \mid X_1] = \mu_2 + \frac{\rho \sigma_2}{\sigma_1} (X_1 \mu_1)$ is linear in $X_1 \rightarrow \text{linear regression}$

Moment Generating Function

Moment generating function: Let X be an r.v. The moment generating function (m.g.f.) of X, denoted by M_X(t), is defined as M_X(t) = ℝ[e^{tX}] if ℝ[e^{tX}] exists for all t ∈ (-s, s) for some s > 0.

• If m.g.f. is given, higher order moments can be easily computed: $\frac{d^k}{M_k} M_k(t) = \mathbb{E}[X^k e^{0X_1}] - \mathbb{E}[X^{k_1}] \text{ for } k = 1, 2$

 $\left. \frac{d^k}{dt^k} M_X(t) \right|_{t=0} = \mathbb{E}[X^k e^{0X}] = \mathbb{E}[X^k], \text{ for } k = 1, 2, \dots$

• If X_1, \dots, X_n are independent, the m.g.f. of $Y \equiv \sum_{i=1}^n X_i$ is $M_Y(t) = \mathbb{E}[e^{t\sum_{i=1}^n X_i}] = \mathbb{E}[\prod_{i=1}^n e^{tX_i}] = \prod_{i=1}^n \mathbb{E}[e^{tX_i}] = \prod_{i=1}^n M_{X_i}(t)$

• M.g.f. uniquely determines the distribution: If r.v.s X_1 and X_2 have m.g.f.s and $M_{X_1}(t) = M_{X_2}(t)$ for all $t \in (-a, a)$ for some a > 0, then c.d.f.s $F_{X_1}(x) = F_{X_2}(x)$ for all x

M.g.f. of Gamma Distributions

- Square of a Gaussian r.v. follows a Gamma distribution
- X follows a Gamma distribution:

• P.d.f.:

$$f_X(x) = rac{eta^{lpha}}{\Gamma(lpha)} x^{lpha-1} \mathrm{e}^{-eta x}$$
 for $x > 0$

- Parameters: Shape a > 0 and rate $\beta > 0$
- Alternative parameterization: Shape a > 0 and scale $\theta = 1/\beta$
- Gamma function: $\Gamma(a) = \int_0^\infty x^{a-1} e^{-x} dx$
- Denoted by: $X \sim \text{Ga}(a, \beta)$
- M.g.f. of the Gamma distribution:

$$\mathbb{E}[e^{tX}] = \frac{\beta^{\alpha}}{\Gamma(\alpha)} \int_{0}^{\infty} x^{\alpha-1} e^{-(\beta-t)x} dx = \frac{\beta^{\alpha}}{\Gamma(\alpha)} \frac{\Gamma(\alpha)}{(\beta-t)^{\alpha}} = \left(\frac{\beta}{\beta-t}\right)^{\alpha}$$

- Expectation and variance: $\mathbb{E}[X] = \alpha/\beta$, $\mathbb{V}[X] = \alpha/\beta^2$
- Sum of independent Gamma r.v.s $X_i \sim Ga(a_i, \beta), i = 1, ..., n$:

$$M_{\sum_{i=1}^{n} X_{i}}(t) = \prod_{i=1}^{n} M_{X_{i}}(t) = \prod_{i=1}^{n} \left(\frac{\beta}{\beta-t}\right)^{\alpha_{i}} = \left(\frac{\beta}{\beta-t}\right)^{\sum_{i=1}^{n} \alpha_{i}}$$
$$\sum_{i=1}^{n} X_{i} \sim \operatorname{Ga}(\sum_{i=1}^{n} \alpha_{i}, \beta)$$

Yuki Shiraito

Sample Moments

- Let X_1, \ldots, X_n is a random sample from a distribution F_X
- In other words, X_1, \ldots, X_n are *data*
- Sample moments: Let X_1, \ldots, X_n be i.i.d. r.v.s. The *k*th sample moment, denoted by M_k , is defined as

$$M_k \equiv \frac{1}{n} \sum_{i=1}^n X_i^k$$

- Why this is important: We never observe F_X , hence neither $\mathbb{E}[X^k]$
- We use *M_k* as an *estimator*–a function of r.v.s, therefore r.v.
- Mean and variance of M_k for any F_X :

$$\mathbb{E}[M_k] = \mathbb{E}[X^k], \quad \mathbb{V}(M_k) = \frac{\mathbb{V}(X^k)}{n}$$

- In particular, for sample mean $\overline{X} \equiv \sum_{i=1}^{n} X_i/n$, $\mathbb{E}[\overline{X}] = \mathbb{E}[X], \quad \mathbb{V}(\overline{X}) = \frac{\mathbb{V}(X)}{n}$
- If we specify F_{X} , we can derive the distribution of M_k

Sample Mean of Gaussian R.v.

- We want to find the distribution of the sum of independent r.v.s ~> use m.g.f.!
- M.g.f. of the Gaussian distribution $\mathcal{N}(\mu, \sigma^2)$:

$$\mathbb{E}[e^{tX}] = \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi\sigma}} e^{-\frac{1}{2\sigma^2}(x-\mu)^2 + tx} dx$$

= $\int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi\sigma}} e^{-\frac{1}{2\sigma^2} \left\{ x - (\mu + \sigma^2 t) \right\}^2 + \mu t + \frac{1}{2}\sigma^2 t^2} dx$
= $e^{\mu t + \frac{1}{2}\sigma^2 t^2} \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi\sigma}} e^{-\frac{1}{2\sigma^2} \left\{ x - (\mu + \sigma^2 t) \right\}^2} dx = e^{\mu t + \frac{1}{2}\sigma^2 t^2}$

• M.g.f. of the sample mean:

$$\mathbb{E}[\mathbf{e}^{t\overline{X}}] = \prod_{i=1}^{n} \mathbb{E}[\mathbf{e}^{\frac{t}{n}X}] = \mathbf{e}^{n\left\{\mu\frac{t}{n} + \frac{1}{2}\sigma^{2}\left(\frac{t}{n}\right)^{2}\right\}} = \mathbf{e}^{\mu t + \frac{1}{2}\left(\frac{\sigma^{2}}{n}\right)t^{2}}$$
$$\Rightarrow \overline{X} \sim \mathcal{N}\left(\mu, \frac{\sigma^{2}}{n}\right)$$