

Simple Linear Regression for Randomized Experiments

Yuki Shiraito

POLSCI 699 Statistical Methods in Political Research II
University of Michigan

Simple Linear Regression Model

- Setup (same as before):
 - ① Units $i = 1, \dots, n$; random sample from superpopulation
 - ② Potential outcomes $(Y_i(0), Y_i(1))$
 - ③ Treatment $T_i \in \{0, 1\}$; completely random assignment

- Simple linear regression model:

$$Y_i = \alpha + \beta T_i + \varepsilon_i, \quad \mathbb{E}(\varepsilon_i) = 0$$

- Y_i : *observed* (not potential) outcome
- Parameters: intercept α , slope β
- ε_i : error term, disturbance, residual
 - $\mathbb{E}(\varepsilon_i) = 0$ is not really an assumption because we have α
- Ordinary least squares (OLS) estimator:

$$(\hat{\alpha}_{\text{OLS}}, \hat{\beta}_{\text{OLS}}) = \underset{a, b}{\operatorname{argmin}} \sum_{i=1}^n (Y_i - a - bT_i)^2$$

Regression and Conditional Expectation

- Conditional expectation minimizes the mean squared error:

$$\mathbb{E}[Y_i | T_i] = \underset{f(T_i)}{\operatorname{argmin}} \mathbb{E} \left[(Y_i - f(T_i))^2 \right]$$

- Linear predictor that minimizes the mean squared error:

$$(\alpha, \beta) \equiv \underset{a, b}{\operatorname{argmin}} \mathbb{E} \left[(Y_i - a - bT_i)^2 \right]$$

- $T_i \in \{0, 1\} \implies \mathbb{E}[Y_i | T_i]$ is either $\mathbb{E}[Y_i | T_i = 0]$ or $\mathbb{E}[Y_i | T_i = 1]$
 - $\mathbb{E}[Y_i | T_i] = \mathbb{E}[Y_i | T_i = 0] + ([Y_i | T_i = 1] - \mathbb{E}[Y_i | T_i = 0])T_i$
 - Population regression parameter $\beta = [Y_i | T_i = 1] - \mathbb{E}[Y_i | T_i = 0]$
- Population regression parameter β is PATE:
 - $\beta = [Y_i | T_i = 1] - \mathbb{E}[Y_i | T_i = 0] = [Y_i(1) | T_i = 1] - \mathbb{E}[Y_i(0) | T_i = 0]$
 - $(Y_i(1), Y_i(0)) \perp\!\!\!\perp T_i \implies \mathbb{E}[Y_i(1) | T_i = 1] - \mathbb{E}[Y_i(0) | T_i = 0] = \mathbb{E}[Y_i(1)] - \mathbb{E}[Y_i(0)] = \text{PATE}$
- OLS estimator as sample analog

More Causal Interpretation

- Association: you can always regress Y_i on T_i and vice versa
- Causal model as **structural equation model**

- Linear model in terms of potential outcomes:

$$Y_i(t) = \alpha + \beta t + \varepsilon_i, \quad \mathbb{E}(\varepsilon_i) = 0$$

- No interference between units
- $\alpha = \mathbb{E}(Y_i(0))$
- $\beta = Y_i(1) - Y_i(0)$ for all $i \iff$ **Constant additive unit causal effect**
- A more general model with **heterogeneous treatment effects**:

$$Y_i(t) = \alpha + \beta_i t + \varepsilon_i = \alpha + \beta t + \underbrace{(\beta_i - \beta)t + \varepsilon_i}_{=\varepsilon_i(t)}$$

where $\mathbb{E}[\varepsilon_i] = 0$ and $\beta = \mathbb{E}[\beta_i] = \text{PATE}$

- Relax the assumption of constant additive unit causal effect
- $\mathbb{E}[\varepsilon_i(t)] = 0$ for $t = 0, 1$
- $\alpha = \mathbb{E}(Y_i(0))$ as before

Assumptions for Linear Regression

- ① Random assignment, $(Y_i(1), Y_i(0)) \perp\!\!\!\perp T_i$ for all i , implies:

$$\mathbb{E}[Y_i(t) | T_i] = \mathbb{E}[Y_i(t)] \iff \mathbb{E}[\varepsilon_i(t) | T_i] = \mathbb{E}[\varepsilon_i(t)] = 0$$

- ② Random sampling of units, $(Y_i(1), Y_i(0)) \perp\!\!\!\perp (Y_j(1), Y_j(0))$ for any (i, j) s.t. $i \neq j$, implies:

$$(\varepsilon_i(1), \varepsilon_i(0)) \perp\!\!\!\perp (\varepsilon_j(1), \varepsilon_j(0)) \text{ for any } (i, j) \text{ s.t. } i \neq j$$

\implies **Strict exogeneity:** $\mathbb{E}[\varepsilon_i | \mathbf{T}] = \mathbb{E}[\varepsilon_i] = 0$ where $\mathbf{T} = (T_1, T_2, \dots, T_n)$

- ① Orthogonality: $\mathbb{E}[\varepsilon_i T_j] = 0$ for any (i, j) (not limited to $i \neq j$)
- ② Zero correlation: $\text{Cov}(\varepsilon_i, T_j) = 0$ for any (i, j) (not limited to $i \neq j$)

- ③ Variance of potential outcomes:

$$\mathbb{V}(\varepsilon_i(t)) = \mathbb{V}(\varepsilon_i(t) | T_i) = \mathbb{V}(Y_i(t) | T_i) = \mathbb{V}(Y_i(t)) = \sigma_t^2 \text{ for } t = 0, 1$$

- $\sigma_0 = \sigma_1 = \sigma$ if constant additive unit causal effect
- $\varepsilon_i(t) = (\beta_i - \beta)t + \varepsilon_i = \varepsilon_i$ if $\beta_i = \beta$ for all i

\implies **Homoskedasticity:** $\mathbb{V}(\varepsilon_i | \mathbf{T}) = \mathbb{V}(\varepsilon_i) = \sigma^2$

Least Squares Estimation

- Model parameters for population regression

$$(\alpha, \beta) \equiv \operatorname{argmin}_{a,b} \mathbb{E} \left[(Y_i - a - bT_i)^2 \right]$$

- Minimization of the **sum of squared residuals** (SSR):

$$\begin{aligned} (\hat{\alpha}_{\text{OLS}}, \hat{\beta}_{\text{OLS}}) &= \operatorname{argmin}_{a,b} \sum_{i=1}^n (Y_i - a - bT_i)^2 \\ &= \operatorname{argmin}_{(a,b)} \sum_{i=1}^n \hat{\varepsilon}_i^2 \end{aligned}$$

- Predicted (fitted) value: $\hat{Y}_i = \hat{\alpha}_{\text{OLS}} + \hat{\beta}_{\text{OLS}}T_i$
- Residual: $\hat{\varepsilon}_i = Y_i - \hat{Y}_i = Y_i - \hat{\alpha}_{\text{OLS}} - \hat{\beta}_{\text{OLS}}T_i$
- OLS estimator (Adam will derive in the section):

$$\hat{\beta}_{\text{OLS}} = \frac{\sum_{i=1}^n (Y_i - \bar{Y})(T_i - \bar{T})}{\sum_{i=1}^n (T_i - \bar{T})^2}$$

$$\hat{\alpha}_{\text{OLS}} = \bar{Y} - \hat{\beta}_{\text{OLS}}\bar{T}$$

Unbiasedness of OLS Estimator

- When T_i is binary, $\hat{\beta}_{OLS}$ = Difference-in-Means estimator (Adam's section)
- So, $\hat{\beta}_{OLS}$ is unbiased for PATE from the design-based perspective
- Is $\hat{\beta}_{OLS}$ unbiased for β , population regression parameter?
 - Yes if T_i is binary, because β is PATE
 - More generally yes, under strict exogeneity and linearity
- Model-based estimation error:

$$\hat{\beta}_{OLS} - \beta = \frac{\sum_{i=1}^n (T_i - \bar{T}) \varepsilon_i}{\sum_{i=1}^n (T_i - \bar{T})^2}$$

- Thus, the exogeneity assumption implies,

$$\mathbb{E} [\hat{\beta}_{OLS}] - \beta = \mathbb{E} [\mathbb{E} [\hat{\beta}_{OLS} - \beta \mid \mathbf{T}]] = 0$$

- Similarly, $\hat{a}_{OLS} - a = \bar{\varepsilon} - (\hat{\beta}_{OLS} - \beta) \bar{T}$
- Thus, $\mathbb{E} [\hat{a}_{OLS}] - a = 0$

Model-based Sampling Variance of OLS Estimator

- The homoskedasticity assumption implies

$$\mathbb{V}(\hat{\beta}_{\text{OLS}} | \mathbf{T}) = \frac{\sigma^2}{\sum_{i=1}^n (T_i - \bar{T})^2}$$

- Standard model-based (conditional) variance estimator for $\hat{\beta}$:

$$\mathbb{V}(\widehat{\hat{\beta}}_{\text{OLS}} | \mathbf{T}) = \frac{\hat{\sigma}^2}{\sum_{i=1}^n (T_i - \bar{T})^2} \quad \text{where} \quad \hat{\sigma}^2 = \frac{1}{n-2} \sum_{i=1}^n \hat{\varepsilon}_i^2$$

- (Conditionally) Unbiased: $\mathbb{E}[\hat{\sigma}^2 | \mathbf{T}] = \sigma^2$ implies

$$\mathbb{E}\left[\mathbb{V}(\widehat{\hat{\beta}}_{\text{OLS}} | \mathbf{T}) \mid \mathbf{T}\right] = \mathbb{V}(\hat{\beta}_{\text{OLS}} | \mathbf{T})$$

- (Unconditionally) Unbiased: $\mathbb{V}(\mathbb{E}[\hat{\beta}_{\text{OLS}} | \mathbf{T}]) = 0$ implies

$$\begin{aligned} \mathbb{V}(\hat{\beta}_{\text{OLS}}) &= \mathbb{E}\left[\mathbb{V}(\hat{\beta}_{\text{OLS}} | \mathbf{T})\right] = \mathbb{E}\left[\mathbb{E}\left[\mathbb{V}(\widehat{\hat{\beta}}_{\text{OLS}} | \mathbf{T}) \mid \mathbf{T}\right]\right] \\ &= \mathbb{E}\left[\mathbb{V}(\widehat{\hat{\beta}}_{\text{OLS}} | \mathbf{T})\right] \end{aligned}$$

Model-Based Asymptotic Inference

- Consistency: $\hat{\beta}_{OLS} \xrightarrow{P} \frac{\text{Cov}(T_i, Y_i)}{\mathbb{V}(T_i)} = \beta$ (c.f. Q3 of PS599 PSet 6)
- Asymptotic distribution and inference:

$$\begin{aligned} \sqrt{n}(\hat{\beta}_{OLS} - \beta) &= \underbrace{\sqrt{n} \left(\frac{1}{n} \sum_{i=1}^n (T_i - \mathbb{E}[T_i]) \varepsilon_i + (\mathbb{E}[T_i] - \bar{T}) \frac{1}{n} \sum_{i=1}^n \varepsilon_i \right)}_{\xrightarrow{d} \mathcal{N}(0, \sigma^2 \mathbb{V}(T_i))} \\ &\quad \times \underbrace{\left(\frac{1}{n} \sum_{i=1}^n (T_i - \bar{T})^2 \right)^{-1}}_{\xrightarrow{P} \mathbb{V}(T_i)^{-1}} \\ &\xrightarrow{d} \mathcal{N} \left(0, \frac{\sigma^2}{\mathbb{V}(T_i)} \right) \end{aligned}$$

$$\frac{\hat{\beta}_{OLS} - \beta}{\text{s.e.}} \xrightarrow{d} \mathcal{N}(0, 1) \text{ where s.e.} = \sqrt{\frac{\hat{\sigma}^2}{\sum_{i=1}^n (T_i - \bar{T})^2}}$$

Violation of Homoskedasticity

- The design-based perspective: use Neyman's exact variance
 - Not relying on constant additive unit causal effect
- Constant additive unit causal effect \implies homoskedasticity
- Heterogeneous effects \implies violation of homoskedasticity \implies bias of model-based variance estimator
- Finite sample bias:

$$\text{Bias} = \underbrace{\mathbb{E} \left(\frac{\hat{\sigma}^2}{\sum_{i=1}^n (T_i - \bar{T})^2} \right)}_{\text{expectation of variance estimator}} - \underbrace{\left(\frac{\sigma_1^2}{n_1} + \frac{\sigma_0^2}{n_0} \right)}_{\text{true variance}}$$

$$= \frac{(n_1 - n_0)(n - 1)}{n_1 n_0 (n - 2)} (\sigma_1^2 - \sigma_0^2)$$

- 1 zero if homoskedasticity holds: $\sigma_1^2 - \sigma_0^2 = 0$
- 2 zero if design is balanced: $n_1 - n_0 = 0$
- 3 not asymptotically zero
- 4 can be negative or positive

Eicker-Huber-White (EHW) Variance Estimator

- **Heteroskedasticity-consistent (HC) variance estimators**
 - also known as “robust” or “sandwich” estimators
 - implemented in sandwich package in **R**

- EHW (or simply “Huber-White”) robust variance estimator:

$$\underset{\text{(EHW)}}{\mathbb{V}} \left(\widehat{\beta}_{\text{OLS}} \mid \mathbf{T} \right) \equiv \left(\sum_{i=1}^n \tilde{\mathbf{T}}_i \tilde{\mathbf{T}}_i^\top \right)^{-1} \left(\sum_{i=1}^n \hat{\varepsilon}_i^2 \tilde{\mathbf{T}}_i \tilde{\mathbf{T}}_i^\top \right) \left(\sum_{i=1}^n \tilde{\mathbf{T}}_i \tilde{\mathbf{T}}_i^\top \right)^{-1}$$

where

$$\tilde{\beta} \equiv \begin{pmatrix} \alpha \\ \beta \end{pmatrix} \text{ and } \tilde{\mathbf{T}}_i \equiv \begin{pmatrix} 1 \\ T_i \end{pmatrix}$$

- Design-based evaluation:

$$\text{Bias} = \mathbb{E} \left[\underset{\text{(EHW)}}{\mathbb{V}} \left(\widehat{\beta}_{\text{OLS}} \mid \mathbf{T} \right) \right] - \left(\frac{\sigma_1^2}{n_1} + \frac{\sigma_0^2}{n_0} \right) = - \left(\frac{\sigma_1^2}{n_1^2} + \frac{\sigma_0^2}{n_0^2} \right)$$

- Negative bias, but vanishes asymptotically

HC2 Variance Estimator

- HC2 robust variance estimator: $\mathbb{V}_{(\text{HC2})} \left(\widehat{\beta}_{\text{OLS}} \mid \mathbf{T} \right)$

$$\equiv \left(\sum_{i=1}^n \tilde{\mathbf{T}}_i \tilde{\mathbf{T}}_i^\top \right)^{-1} \left(\sum_{i=1}^n \frac{\hat{\varepsilon}_i^2}{1 - \rho_{ii}} \tilde{\mathbf{T}}_i \tilde{\mathbf{T}}_i^\top \right) \left(\sum_{i=1}^n \tilde{\mathbf{T}}_i \tilde{\mathbf{T}}_i^\top \right)^{-1}$$

where

$$\rho_{ii} = \tilde{\mathbf{T}}_i^\top \left(\tilde{\mathbf{T}}^\top \tilde{\mathbf{T}} \right) \tilde{\mathbf{T}}_i = \begin{cases} \frac{1}{n_1} & \text{if } T_i = 1 \\ \frac{1}{n_0} & \text{if } T_i = 0 \end{cases}$$

- ρ_{ii} is the (i, i) element of the *projection matrix* (discussed later)
- Samii and Aronow (2012):

$$\mathbb{V}_{(\text{HC2})} \left(\widehat{\beta}_{\text{OLS}} \mid \mathbf{T} \right) = \frac{\hat{\sigma}_1^2}{n_1} + \frac{\hat{\sigma}_0^2}{n_0}$$

- HC2 estimator is identical Neyman's estimator

Cluster Randomized Experiments

- Units: $i = 1, 2, \dots, n_j$
- Clusters of units: $j = 1, 2, \dots, m$
- Treatment at cluster level: $T_j \in \{0, 1\}$
- Outcome: $Y_{ij} = Y_{ij}(T_j)$
- Random assignment: $(Y_{ij}(1), Y_{ij}(0)) \perp\!\!\!\perp T_j$
- **No interference** between units of different clusters
- Possible interference between units of the same cluster
- Random sampling of clusters and units
- Estimands at unit level:

$$\text{SATE} \equiv \frac{1}{\sum_{j=1}^m n_j} \sum_{j=1}^m \sum_{i=1}^{n_j} (Y_{ij}(1) - Y_{ij}(0))$$

$$\text{PATE} \equiv \mathbb{E} [Y_{ij}(1) - Y_{ij}(0)]$$

Design-Based Inference

- For simplicity, assume the following:
 - ① equal cluster size, i.e., $n_j = n$ for all j
 - ② we observe all units for a selected cluster (no sampling of units)
- The difference-in-means estimator:

$$\hat{\tau} \equiv \frac{1}{m_1} \sum_{j=1}^m T_j \bar{Y}_j - \frac{1}{m_0} \sum_{j=1}^m (1 - T_j) \bar{Y}_j$$

where $\bar{Y}_j \equiv \sum_{i=1}^n Y_{ij} / n$

- Easy to show $\mathbb{E}(\hat{\tau} \mid \mathcal{O}) = \text{SATE}$ and thus $\mathbb{E}(\hat{\tau}) = \text{PATE}$
- Exact population variance:

$$\mathbb{V}(\hat{\tau}) = \frac{\mathbb{V}(\overline{Y_j(1)})}{m_1} + \frac{\mathbb{V}(\overline{Y_j(0)})}{m_0}$$

Intraclass Correlation Coefficient

- Comparison with the standard variance:

$$\mathbb{V}(\hat{\tau}) = \frac{\sigma_1^2}{m_1 n} + \frac{\sigma_0^2}{m_0 n}$$

- Correlation of potential outcomes across units within a cluster

$$\begin{aligned} \mathbb{V}(\overline{Y_j(t)}) &= \mathbb{V}\left(\frac{1}{n} \sum_{i=1}^n Y_{ij}(t)\right) \\ &= \frac{1}{n^2} \left\{ \sum_{i=1}^n \mathbb{V}(Y_{ij}(t)) + \sum_{i \neq i'} \sum_{i'=1}^n \text{Cov}(Y_{ij}(t), Y_{i'j}(t)) \right\} \\ &= \frac{\sigma_t^2}{n} \{1 + (n-1)\rho_t\} \stackrel{\text{typically}}{\geq} \frac{\sigma_t^2}{n} \end{aligned}$$

Cluster Standard Error

- Cluster robust variance estimator: $\mathbb{V}_{(\text{Cluster})} \left(\widehat{\beta}_{\text{OLS}} \mid \mathbf{T} \right)$

$$= \left(\sum_{j=1}^m \mathbf{T}_j^{\top} \mathbf{T}_j \right)^{-1} \left(\sum_{j=1}^m \mathbf{T}_j^{\top} \hat{\varepsilon}_j \hat{\varepsilon}_j^{\top} \mathbf{T}_j \right) \left(\sum_{j=1}^m \mathbf{T}_j^{\top} \mathbf{T}_j \right)^{-1}$$

where

$$\hat{\varepsilon}_j = \begin{pmatrix} \hat{\varepsilon}_{1j} \\ \vdots \\ \hat{\varepsilon}_{nj} \end{pmatrix} \text{ and } \mathbf{T}_j = \begin{pmatrix} 1 & T_{1j} \\ \vdots & \vdots \\ 1 & T_{nj} \end{pmatrix}$$

- Design-based evaluation:

$$\text{Bias} = - \left(\frac{\mathbb{V} \left(\overline{Y_j(1)} \right)}{m_1^2} + \frac{\mathbb{V} \left(\overline{Y_j(0)} \right)}{m_0^2} \right)$$

- Bias vanishes asymptotically as $m \rightarrow \infty$ with n fixed
- Implication:** cluster by the unit of treatment assignment